Sensorless BLDC Motor Control Based on MC9S08PT60 Tower Board

User Guide

1 Overview

This user guide describes the basic steps for getting started with the sensorless BLDC motor control based on MC9S08PT60 Tower Board demo. The basic board function is described in this document.

The whole system is composed of TWR-S08PT60 and TWR-MC-LV3PH (3-phase low voltage motor control board).

TWR-S08PT60 is a low-cost evaluation, demonstration and development board that features the 8-bit MC9S08PT60 microcontroller. The MC9S08P series are members of the low-cost, high-performance S08 family of 8-bit microcontroller units (MCUs). The MC9S08PT60 has up to 60 KB flash memory, 256 byte EEPROM, 4 KB RAM, and has a large set of peripherals including timers (3FTMs, 2 MTIMs), 3 SCIs (UARTs), 2 SPIs, I2C, ADC, ACMP, KBI, TSI, and others.

The following figure presents the block diagram of MC9S08PT60 Tower board.

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Overview

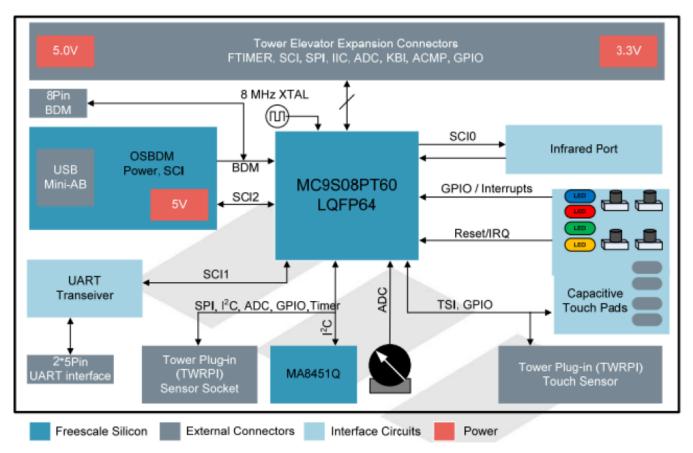


Figure 1. TWR-S08PT60 block diagram

The 3-phase Low Voltage Motor Control Board (TWR-MC-LV3PH) is a peripheral Tower System module. Figure 2 presents the block diagram of TWR-MC-LV3PH.

Following are the features of the TWR-LV3PH.

- Power supply voltage input 12-24 V DC, extended up to 50 V.
- Output current up to 8 A
- Power supply reverse polarity protection circuitry
- 3-phase bridge inverter (6-MOSFETs)
- 3-phase MOSFET gate driver with over current and under voltage protection
- 3-phase and DC bus current-sensing shunts
- DC bus-voltage sensing
- 3-phase back-EMF voltage sensing circuitry
- Encode / hall sensor sensing circuitry
- Motor power and signal connectors
- User LED, power-on LED, and 6 PWM LED diodes

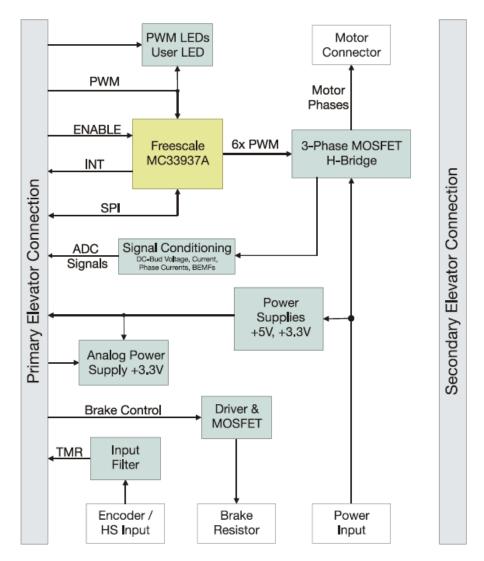


Figure 2. TWR-MC-LV3PH block diagram

2 Demo boards

The following figures depict the TWR-S08PT60 and TWR-MC-LV3PH demo boards labelled with the different components.

Demo boards

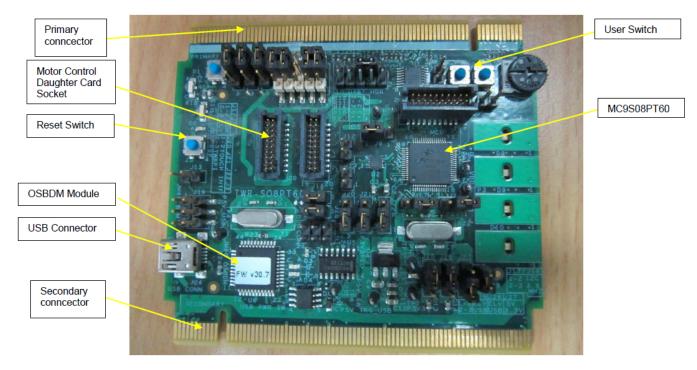


Figure 3. TWR-S08PT60 demo board

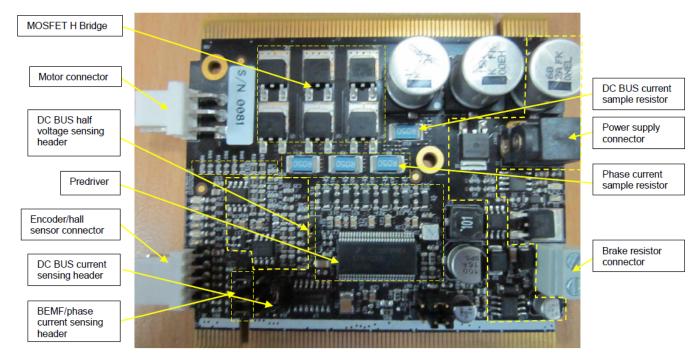


Figure 4. TWR-MC-LV3PH demo board

3 Hardware feature

3.1 TWR-S08PT60

3.1.1 System power

The TWR-S08PT60 can be powered by the OSBDM circuit Mini-B USB connector when running in standalone mode. When assembled with the Tower System, the TWR-S08PT60 is powered by the Tower System Elevators. The mini-B USB connector is no longer used as a power source and is only used for OSBDM debugging purposes.

When working in standalone mode, short pins 2 and 3 on J25 and J26 jumper blocks as the default setting. When working with the Tower System, short pins 1 and 2 on both J25 and J26 jumper blocks, as shown in the following figure.

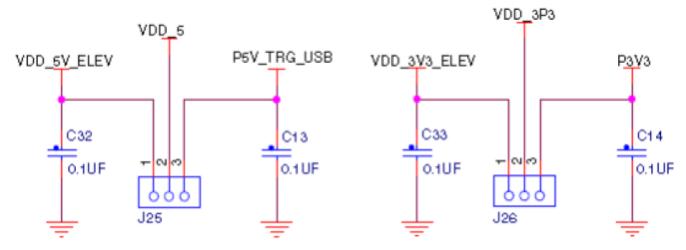


Figure 5. Power supply selection for standalone or Tower Elevator

The PT60 can be powered by 5 V or 3.3 V power supply which is configurable via jumper J27. To use 5 V power supply, short pins 1 and 2 and to use 3.3 V power supply, short pins 2 and 3. See the following figure.

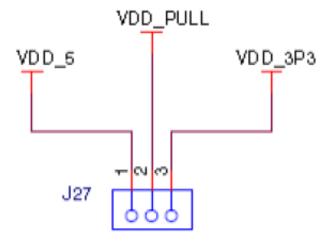


Figure 6. Power supply selection for 5 V or 3.3 V

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TWR-S08PT60

In this application, VDD_3V3_ELEV is selected as power supply according to TWR-MC-LV3PH's configuration. So, short pins 1 and pin 2 of J26, and short pins 2 and 3 of J27.

3.1.2 Push buttons

There are two general-purpose buttons which can be used to evaluate keyboard interrupts, and general switch inputs: SW2 and SW3. SW2 is connected to KBIP5 pin of PT60 and SW3 to KBIP4 pin of PT60.

In addition, there is a reset button (SW4) used to reset PT60 and a force BDM button (SW1) used to manually force PT60 into BDM upon power up or reset.

In this application, SW2 is used to increase speed.

3.1.3 Potentiometer

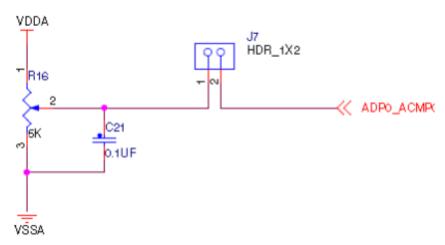


Figure 7. TWR-S08PT60 potentiometer to ADC input

A potentiometer is connected to the ADC input channel ADP0 through a jumper J7 as shown in Figure 7.

In this application, the jumper J7 must be open, because DC_Bus current sample AD channel is conflicting with it.

3.1.4 Jumper tables

The following table shows the jumper settings of TWR-S08PT60 demo board.

Table 1. TWR-S08PT60 jumper settings

Jumper	Option	Setting	Description of MC9S08PT60 signal routing
J1	UART2 selection	1–2	Connect RXD2 to OSBDM UART RX
J2	UART2 selection	1–2	Connect TXD2 to OSBDM UART TX
J3	ACMP1 Selection	1–2	ACMP1 is connected to Touch pad TWRPI pin18 of J8.
		2–3	ACMP1 is optionally connected to motor control TWRPI pin15 of J10.
J4	UART transceiver loop	1–2	U1(ICL3232) pin 9 and pin 10 are shorted.

Table continues on the next page...

Table 1. TWR-S08PT60 jumper settings (continued)

Jumper	Option	Setting	Description of MC9S08PT60 signal routing
J5	UART/TSI/IRDA selection	1–2	UART1 TXD signal is connected to primary elevator A44.
		2–3	UART1 TXD signal is connected to U1(ICL3232) pin11.
		4–5	UART1 RXD signal is connected to primary elevator A43.
		5–6	UART1 TXD signal is connected to U1(ICL3232) pin12.
		7–8	PTB0/KBI0P4/RXD0/ADP4/TSI2 pin is connected to pin3 of J8.
		8–9	PTB0/KBI0P4/RXD0/ADP4/TSI2 pin is connected to IRDA RX.
		10–11	PTB1/KBI0P5/TXD0/ADP5/TSI3 pin is connected to pin5 of J8.
		11–12	PTB1/KBI0P5/TXD0/ADP5/TSI3 pin is connected to IRDA TX.
		13–14	Open
		14–15	IRDA RX is connected to PTA1/KBI0P1/ FTM0CH1/ ACMP1/ADP1 pin.
J7	PTA0/KBIP0/FTM0CH0/ACMP0/ ADP0 Pin selection	1–2	Potentiometer is connected to PTA0/KBI0P0/ FTM0CH0/ACMP0/ADP0 pin.
		open	
J9		1–2	Slave Address (SA0 = 1) 0011101 (0x1D)
		2–3	Slave Address (SA0 = 0) 0011100 (0x1C)
J12		1–2	KBIP4 pin(PT60 pin44) is connected to U2(MMA8451Q) pin11
J13	OSBDM Boot loader mode or debugger mode selection	1–2	OSBDM IC in boot loader mode(For OSBDM firmware reprogramming)
		open	OSBDM IC in debugger mode
J15	KBIP4 Pin selection	1–2	KBIP4 pin(PT60 pin44) is connected to U2(MMA8451Q) pin11
J20	FTM2CH0 or TSI6 function selection	1–2	PTC0/FTM2CH0/ADP8/TSI6 pin is connected to pin9 of J8.
		2–3	PTC0/FTM2CH0/ADP8/TSI6 pin is connected to pin14 of J11.
J21	FTM2CH1or TSI7 function selection	1–2	PTC1/FTM2CH1/ADP9/TSI7 pin is connected to pin10 of J8.
		2–3	PTC1/FTM2CH1/ADP9/TSI7 pin is connected to pin15 of J11.
J22	ADP15 Pin selection	1–2	ADP15 pin is connected to pin 7 of J8.
		2–3	ADP15 pin is connected to pin 17 of J8.
J25	VDD_5 selection	1–2	Elevator +5 V is connected to VDD_5V
		2–3	USB +5 V is connected to VDD_5V.

Table continues on the next page...

Table 1. TWR-S08PT60 jumper settings (continued)

Jumper	Option	Setting	Description of MC9S08PT60 signal routing
J26	VDD_3P3 selection	1–2	Elevator +3.3 V is connected to VDD_3P3
		2–3	LDO U4 output voltage +3.3 V is connected to VDD_3P3
J27	VDD_PULL selection	1–2	VDD_PULL is connected to +5 V.
		2–3	VDD_PULL is connected to +3.3 V.
J28	Reset signal for MC9S08PT60	1–2	Reset signal is connected to RESET pin.
J29	MC9S08PT60 Power Supply	1–2	VDD is connected to VDD_PULL.

In addition to the above mentioned, other jumper's configuration is default. For more information, see TWRS08PT60UM: TWR-S08PT60 User Manual, available on **freescale.com**.

3.2 TWR-MC-LV3PH

3.2.1 Back EMF signals

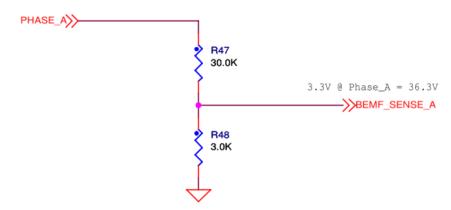


Figure 8. BEMF detect circuit for Phase A

Figure 8 is back EMF detect circuit of phase A, phase B, and phase C are the same.

In this demo, short pins 2 and 3 of the jumpers J11, J12, and J13, otherwise, sample value is phase current value instead of BEMF value.

3.2.2 DC_Bus voltage signals

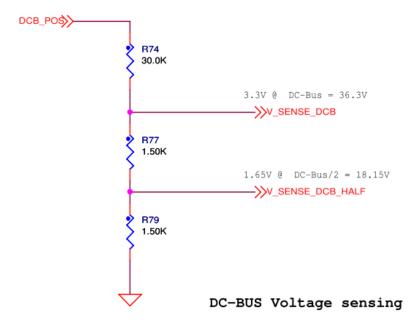


Figure 9. DC_Bus voltage detect circuit

Figure 9 is DC_Bus voltage detect circuit.

In this demo, short pins 2 and 3 of the jumper J14, otherwise, sample value is phase A current value instead of V_SENSE_DCB_HALF.

3.2.3 DC_Bus current signals

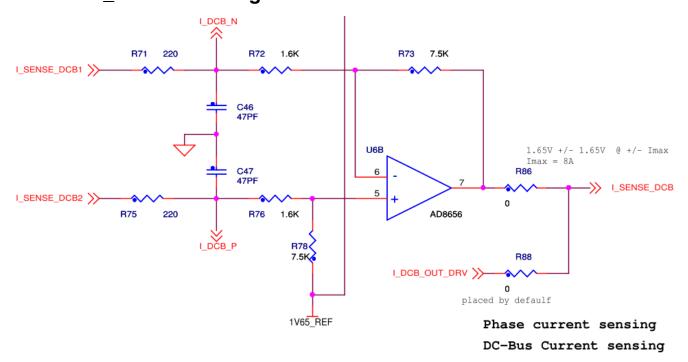


Figure 10. DC_Bus current detect circuit

Figure 10 is DC_Bus current detect circuit.

Conclusions

In this demo, short pins 2 and 3 of the jumper J13, otherwise, sample value is phase C current value instead of I_SENSE_DCB.

3.2.4 Jumper tables

Table 2. TWR-MC-LV3PH jumper settings

Jumpers	Options	Setting	Description of TWR-MC-LV3PH
J2	VDDA Source Select	1–2	Internal on-board source of analog 3.3 V
		2–3	Elevator source of analog 3.3
J3	VSSA Source Select	1–2	Internal on-board source of analog GND
		2–3	Elevator source of analog GND
J10	AN2 Signal Select	1–2	Phase C current signal
		2–3	Back EMF phase C
J11	AN1 Signal Select	1–2	Phase B current signal
		2–3	Back EMF phase B
J12	AN0 Signal Select	1–2	Phase A current signal
		2–3	Back EMF phase A
J13	AN6 Signal Select	1–2	Phase C current signal
		2–3	DC Bus Current
J14	AN56 Signal Select	1–2	Phase A current signal
		2–3	DC Bus Half Voltage

In addition to the above mentioned, other jumpers' configuration is default. For more information, see TWR-MC-LV3PH User's Manual, available on **freescale.com**.

4 Conclusions

This document described the basic steps for getting started with the sensorless BLDCM control based on MC9S08PT60 tower board and its demo suitcase.

5 Reference documents

For the latest revision of all the Tower documents listed below, visit freescale.com.

- TWR-S08PT60 Design Package
- TWRS08PT60QSG: TWR-S08PT60 Quick Start Guide
- TWR-S08PT60-LABS: TWR-S08PT60 Labs
- TWRS08PT60UM: TWR-S08PT60 User Manual
- MC9S08PT60RM: MC9S08PT60 Reference Manual
- MC9S08PT60: MC9S08PT60 Series Data Sheet
- TWRMCLV3PHUG: TWR-MC-LV3PH User's Guide
- TWR-MC-LV3PH Design Package

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Freescale Semiconductor
Technical Information Center, EL516
2100 East Elliot Road
Tempe, Arizona 85284
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Freescale Halbleiter Deutschland GmbH Technical Information Center Schatzbogen 7 81829 Muenchen, Germany +44 1296 380 456 (English) +46 8 52200080 (English) +49 89 92103 559 (German) +33 1 69 35 48 48 (French) www.freescale.com/support

Japan:

Freescale Semiconductor Japan Ltd. Headquarters ARCO Tower 15F 1-8-1, Shimo-Meguro, Meguro-ku, Tokyo 153-0064 Japan 0120 191014 or +81 3 5437 9125 support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor China Ltd.
Exchange Building 23F
No. 118 Jianguo Road
Chaoyang District
Beijing 100022
China
+86 10 5879 8000
support.asia@freescale.com

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